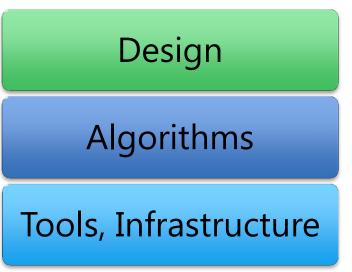
A Tutorial on: Assisted Living Technologies for Older Adults

Speaker: Parisa Rashidi University of Florida

Outline

- * Introduction
- * Technologies, tools, infrastructure
- * Algorithms
- * Use Cases
- * Design Issues
- * Future



This Tutorial is about ...

- * Assisted living technologies for older adults, a.k.a
 - * Gerontechnology
 - * Gerontology + Technology
 - * AAL: Ambient Assisted Living
 - * Assisted Living + Ambient Intelligence



Introduction

Why Important?

* Scope

- * 8.5 million seniors require some form of assistive care
 - * 80% of those over 65 are living with at least one chronic disease
 - * Every 69 seconds someone in America develops Alzheimer's disease

* Costs

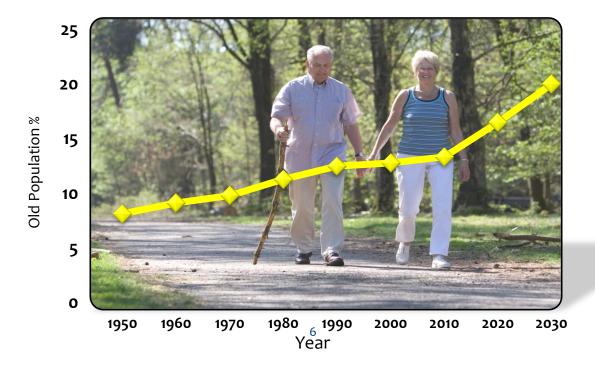
- * Alzheimer's Disease: \$18,500-\$36,000
- * Nursing home care costs: \$70,000-80,000 annually
- * Annual loss to employers: \$33 billion due to working family care givers

Caregiver gap

- * Nurses shortage: 120,000 and 159,300 doctors by 2025
- * Understaffed nursing homes: 91%
- * Family caregivers in US: 31% of households
 - * 70% of caregivers care for someone over age 50

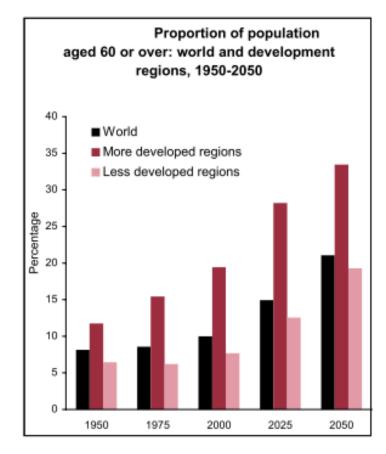
Why Important?

- * By 2030, 1 in 5 Americans will be age 65 or older
 - * Average life expectancy 81 years
 - * By 2040: Alzheimer related costs will be 2 trillion dollars



Why Important?

* By 2050, 1 in 5 person in the world will be age 60 or older



UN Report, Department of Economic and Social Affairs, Population Division, 2001 http://www.un.org/esa/population/publications/worldageing19502050/

Consequences

- * An increase in age-related disease
- * Rising healthcare costs
- Shortage of professionals
- Increase in number of individuals unable to live independently
 - Facilities cannot handle coming "age wave"



Independent Life



Older Adults Challenges

Normal age related challenges

- Physical limitations
 - * Balance, reaching, etc.
- * Perceptual
 - * Vision, hearing
- * Cognitive
 - * Memory, parallel tasks
- * Chronic age related diseases
 - * Alzheimer's Disease (AD)



Older Adults Needs

- * They need help with daily activities
 - Activities of Daily Living (ADL)
 - * e.g. Personal grooming
 - Instrumented Activities of Daily Living (IADL)
 - * e.g. Transportation, cooking
 - * Enhanced Activities of Daily Living (EADL)
 - * e.g. Reading, social engagement
- * Memory Functions
- Health monitoring
- * Removing the burden from caregiver



Tools and Infrastructure

Tools & Infrastructure

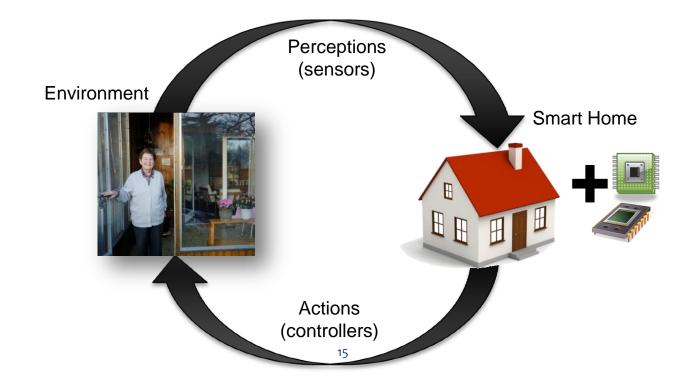
- * What makes Ambient Assisted Living (AAL) possible?
 - * Smart homes
 - * Mobile devices
 - * Wearable sensors
 - * Smart fabrics
 - * Assistive robotics



Tools & Infrastructure: "Smart Homes"

Smart Homes

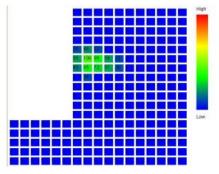
- * Sensors & actuators integrated into everyday objects
- * Knowledge acquisition about inhabitant



Smart Home Sensors

- * PIR (Passive Infrared Sensor)
- * RFID
- * Ultrasonic
- * Pressure sensors (in beds, floor)
- * Contact switch sensors



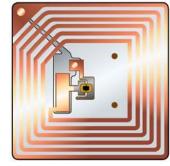


A) A photo of the floor

B) Floor Sensor Data

Floor Pressure Sensor. Noguchi et al. 2002





RFID



Ultrasonic

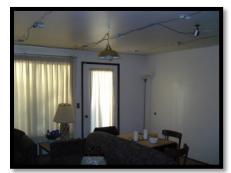
Example Smart Homes

* US

- * Aging in Place, TigerPlace (U. of Missouri), Aware Home (Georgia Tech), CASAS (Washington State U.), Elite Care (OHSU, OR), House_n (MIT)
- * Asia
 - * Welfare Techno House (Japan), Ubiquitous Home (Japan)
- * Europe
 - * iDorm (University of Essex), HIS (France)



Takaoka Welfare Techno House



CASAS, WSU



Aware Home, GaTech

Tools & Infrastructure: "Wearable & Mobile Devices"

Wearable & Mobile Sensors

* Applications

- * Health monitoring
- Navigation and stray prevention
- Mobile persuasive technologies









→ after integration onto skin →

after deformation

Epidermal Electronics, 2011

LifeShirt By Vivometrics®

AMON, 2003, ETH Zurich

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Measurements & Sensors

Movement

- Accelerometer
- Gyroscope

Biochemical

- Stress markers (lactate in sweat)
- Wound healing (pH and infection markers)

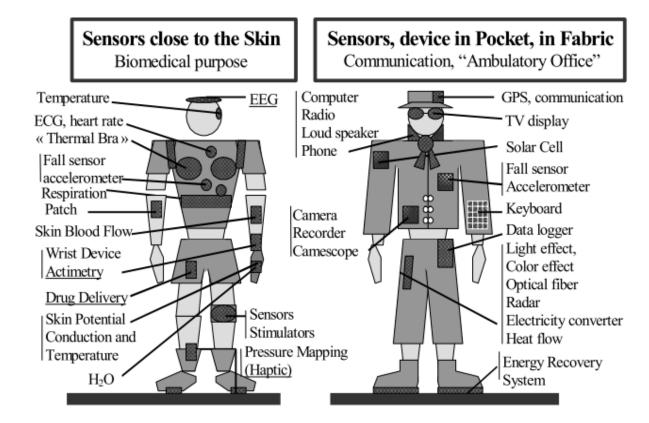
Vital Signs

- Respiration sensors
- Thermal sensors
- Galvanic skin response (GSR) sensors
- Cardiac Activity
 - Pulse oximeter
 - ECG devices
 - Doppler radars



Wearable Device Types

- Holter type
- * Patches
- * Body-worn
- * Smart garments
 - * Garment level
 - * Fabric level
 - * Fiber level



*A. Dittmar; R. Meffre; F. De Oliveira; C. Gehin; G. Delhomme; , "Wearable Medical Devices Using Textile and Flexible Technologies for Ambulatory Monitoring," Engineering in Medicine and Biology Society, 2005. IEEE-EMBS 2005. 27th Annual International Conference of the , vol., no., pp.7161-7164, 2005

Data Transfer Architecture

* Most common setup

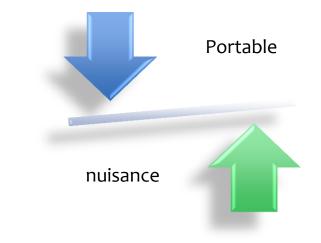
- Sensors on body + a handheld or wearable data hub to communicate data wirelessly + a central node to process data
- * Short range standards
 - Bluetooth (IEEE 802.15.1)
 - ZigBee (IEEE 802.15.4)
- * Short range technologies
 - RF
 - Inductive links, Intrabody Communication



Why Wearable and Mobile?

* Pros.

- * Anywhere, anytime
- * Portable
- * Continuous recordings rather than "snapshot "
- * Avoid "white coat" syndrome
- * Cons.
 - * Anywhere, anytime
 - * Should be worn/carried all the time
 - * Wearing a tag can be regarded as stigma
 - * Privacy concern, 24/7 monitoring



Tools & Infrastructure: "Robots"

Assistive Robotics

- Helpful in physical tasks
- * Communication
 - * People consider them as social entities.



Care-O-bot[®] by Fraunhofer IPA: grasping items and bringing them to resident



RIBA, Japan: Transferring patients, 2009



PARO by U Penn, 2011

How Robots Help with ADL?

Task	# Robots
Support movement	35
Reducing need for movement	34
Feeding	7
Grooming	6
Bathing	4
Toileting	3
Dressing	2

Data from Understanding the potential for robot assistance for older adults in the home environment (HFA-TR-1102). Smarr, C. A., Fausset, C. B., Rogers, W. A. (2011). Atlanta, GA: Georgia Institute of Technology, School of Psychology, Human Factors and Aging Laboratory. Link.

Example ADL Assistive Robots

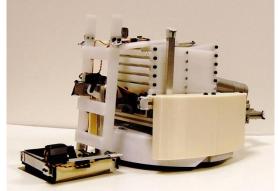
* Reducing the need for movement



Topio Dio by Tosy



Care-O-bot[®] by Fraunhofer IPA: grasping items and bringing them to resident



Dusty II by GA Tech: Retrieving objects from floor

How Robots Help with IADL?

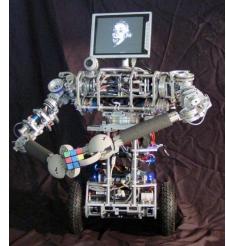
Task	# Robots
Housekeeping	53
Meal preparation	14
Medication Management	13
Laundry	7
Shopping	5
Telephone use	4
Money Management	0
Transportation	0

Data from Understanding the potential for robot assistance for older adults in the home environment (HFA-TR-1102). Smarr, C. A., Fausset, C. B., Rogers, W. A. (2011). Atlanta, GA: Georgia Institute of Technology, School²⁶ Psychology, Human Factors and Aging Laboratory. Link.

Example IADL Assistive Robots



PERMMA by U Penn, 2011



uBot-5 by UMAss, 2011



Roomba by iRobot, 2011

How Robots Help with EADL?

Task	# Robots
Social Communication	46
Hobbies	29
New Learning	16

Data from Understanding the potential for robot assistance for older adults in the home environment (HFA-TR-1102). Smarr, C. A., Fausset, C. B., Rogers, W. A. (2011). Atlanta, GA: Georgia Institute of Technology, School ³ Psychology, Human Factors and Aging Laboratory. Link.

Example EADL Assistive Robots



PARO, Japan, 1993



Pearl by CMU, 2002



iCat by Philips, 2006

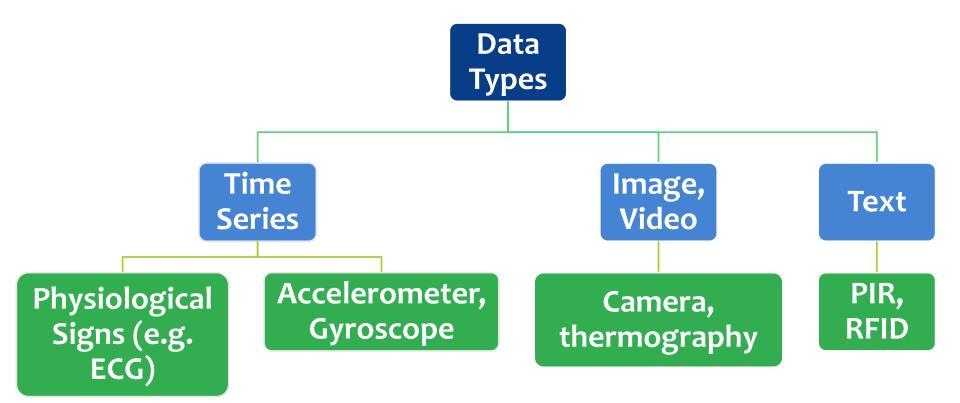
Algorithms & Methods

Algorithms

- * The ones we will discuss
 - * Activity recognition from
 - * Wearable & mobile sensors
 - * Ambient sensors
 - * Camera (Vision)
 - * Context Modeling
 - Other algorithms
 - Indoor Location detection
 - * Reminding



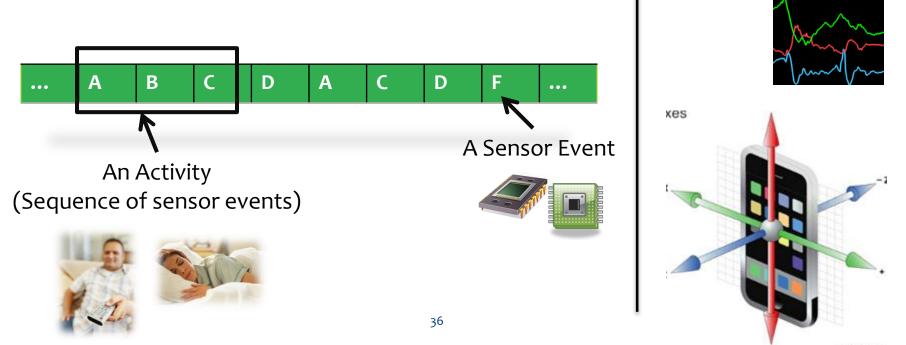
* Different mediums generate different types of data



Algorithms & Methods: "Activity Recognition"

What is Activity Recognition?

- * The basic building block in many applications
 - Recognizing user activities from a stream of sensor events



Activity Resolution

* Fine grained (individual movements, especially in vision)
* Coarse grained (activity)

Movement: e.g. stretching arm

Action: e.g. walking

Activity: e.g. preparing meal

Group Activity: e.g. team sports

Crowd Activity: e.g. crowd surveillance

Complexity

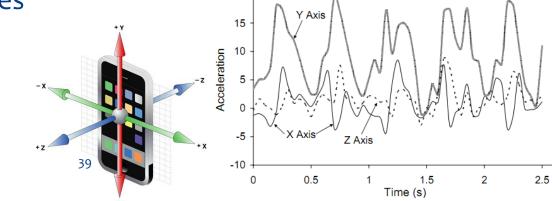
Algorithms & Methods: Activity Recognition: "Wearable & Mobile"

Activity Data from Wearable Sensors

- Mostly in form of time series
 - * Accelerometer [& gyroscope]
- * Most actions in form of distinct, periodic motion patterns
 - * Walking, running, sitting,...
- Usual features

*

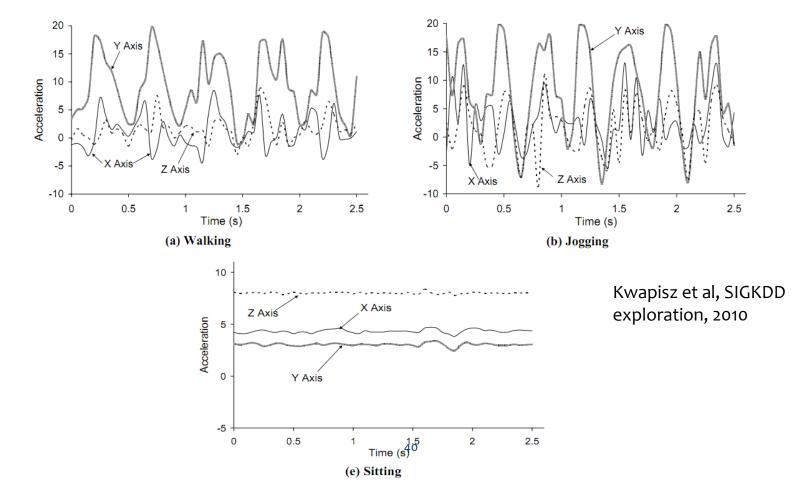
- * Average, standard deviation
- * Time between peaks, FFT energy, Binned distribution
- Correlation between axes



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Example Activities

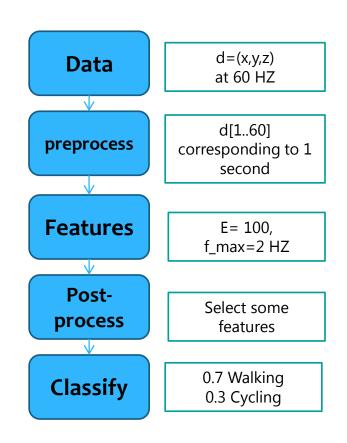
* Example activities from mobile phone accelerometer



Processing Steps

* Stages

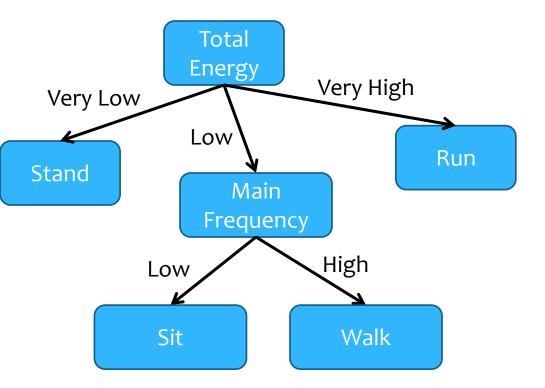
- Data collection
- Preprocessing
- * Feature extraction
 - * Mean, SD, FFT coefficients
- Dimensionality Reduction
- Classification



*See: A Tutorial Introduction to Automated Activity and Intention Recognition by Sebastian Bader, Thomas Kirste. Link

Classification

- * Supervised
 - * SVM, DT, ...
- * Semi-supervised
- * Unsupervised
 - * Clustering
 - * Motif discovery



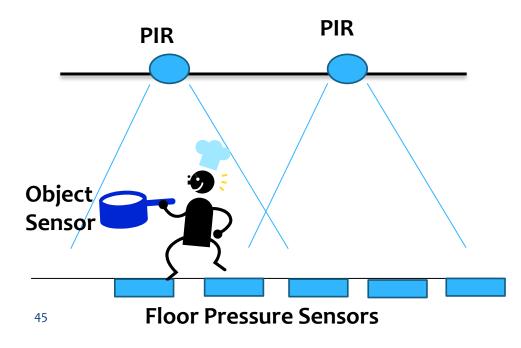
A simple decision tree

*See: A Tutorial Introduction to Automated Activity and Intention Recognition by Sebastian Bader, Thomas Kirste. Link

Algorithms & Methods: Activity Recognition: "Ambient Sensors"

Activity Recognition

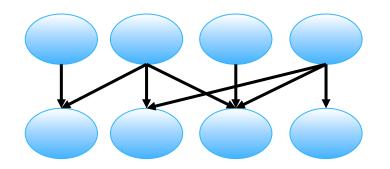
- * More complex activities need more sophisticated sensors
 - * Sensor networks of PIR sensors, contact switch sensors, pressure sensors, object sensors, etc.
- * Approaches
 - * Supervised
 - * Probabilistic
 - * Semi/Unsupervised

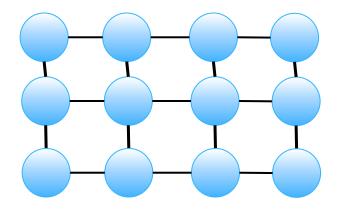


Probabilistic Approaches

Graphical models

- Naïve Bayes (NB)
- * Hidden Markov Model (HMM)
- * Dynamic Bayesian Network (DBN)
- * Conditional Random Field (CRF)





Naïve Bayes

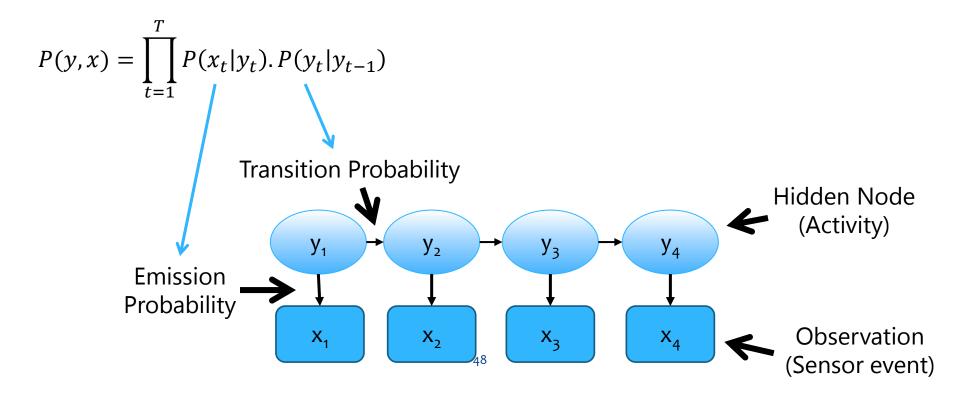
- * A very simple model, yet effective in practice [Tapia 2004]
- * Assumes observations are independent of each other
- * Y = activity (e.g. taking medications)
- * X = observation (e.g. sensor M1 is ON)

$$P(y|x) = P(y) \prod_{m=1}^{M} P(x_m|y)$$

Hidden Markov Model (HMM)

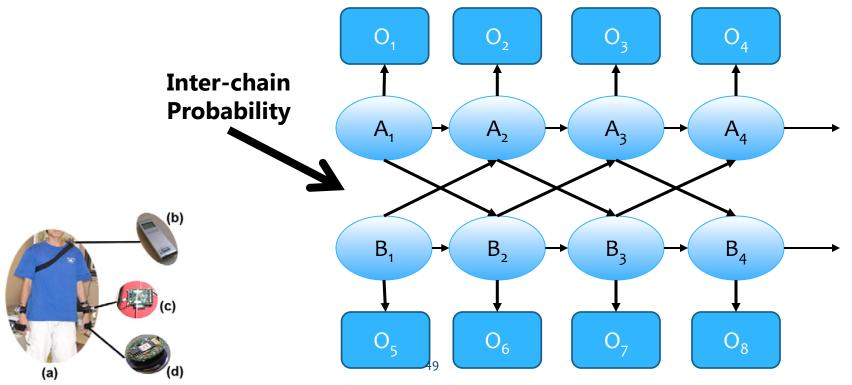
* A model for inferring hidden states from observations

* Well known, efficient algorithms



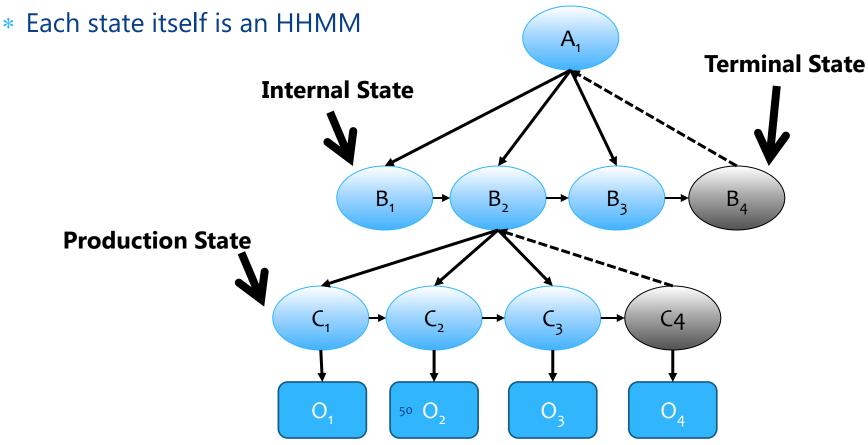
Multiple Residents?

- * Coupled Hidden Markov Model (CHMM) [Wang 2010]
 - * O = observations
 - * A, B = activities



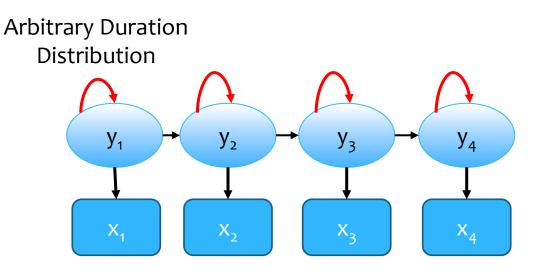
Hierarchal Definition of Activities?

 * Hierarchal Hidden Markov Model (HHMM) [Choo 2008, Nguyen 2006]



Hidden Semi-Markov Model

- * Hidden Semi-Markov Model (HSMM) [Duong 2006]
- Activity duration modeling
 - * Arbitrary probability distribution of staying in a state



Markov Logic Network

- * Markov logic networks [Helaoui 2011]
 - Easily including background knowledge of activities + non-deterministic approach
 - * First order logic + Markov network

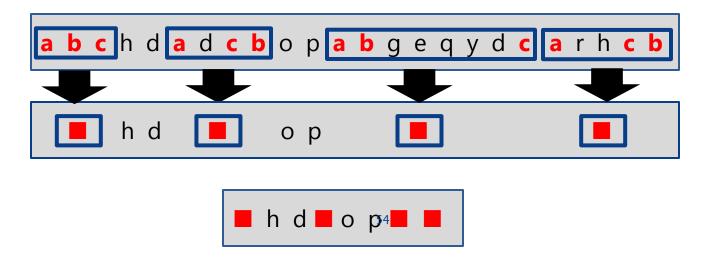


Other Graphical Models

- * Dynamic Bayesian Network (DBN)
- * Conditional Random Fields (CRF)
- * ...

Unsupervised Methods

- * Data annotation problem!
- Emerging patterns
 - * Mining frequent patterns [Gu 2009, Heierman 2003]
 - * Mining periodic sequential patterns [Rashidi 2008]
- * Stream mining
 - * Tilted time model [Rashidi 2010]



Other Techniques

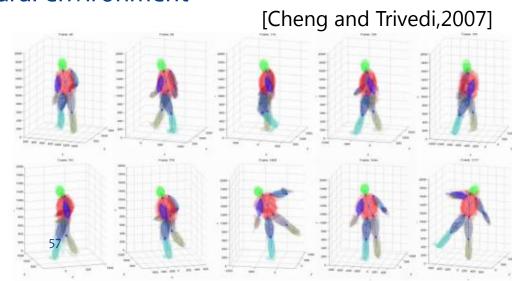
* Transfer learning [TLM van Kastere 2010, VW Zheng 2009]

- Bootstrap for a new resident
- Bootstrap in a new building
- * ...
- * Semi-supervised learning [D Guan 2007,]
 - * Co-training
- * Active learning [M Mandaviani 2007, Rashidi 2011]

Algorithms & Methods: Activity Recognition: "Vision"

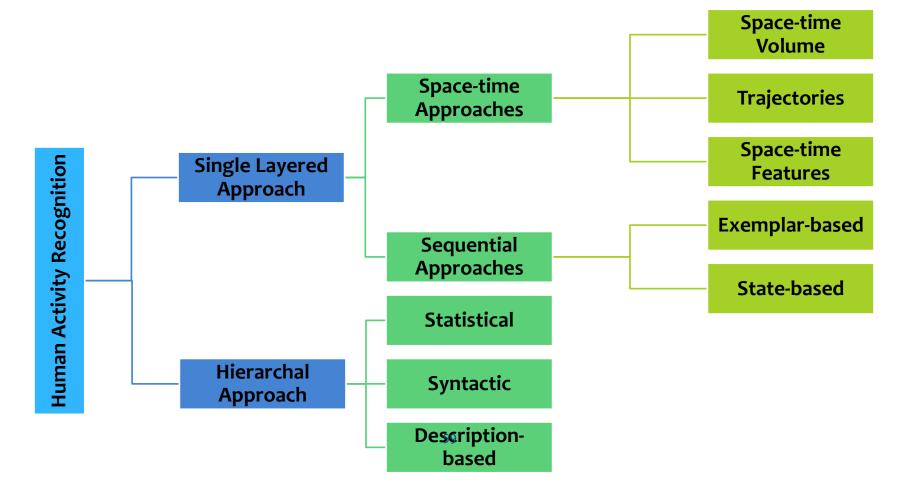
Vision Based Systems

- * Used in many related application domains
 - * Video surveillance, sports analysis, ...
- * Advantages
 - * Rich information
- * Disadvantages
 - * Highly varied activities in natural environment
 - * Privacy concerns
 - Algorithm complexity



Algorithms

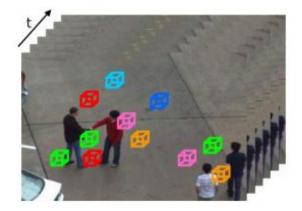
* Taxonomy of methods [Aggarwal & Ryoo 2011]



Single Layered

- * Suitable for recognition of gestures & actions
- * Two different representations
 - * Space-time distribution
 - * Data oriented, spatio-temporal features
 - * Sequence
 - * Semantic oriented, tracking

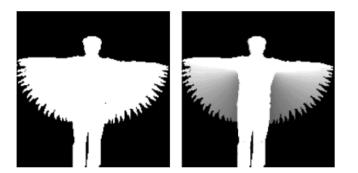




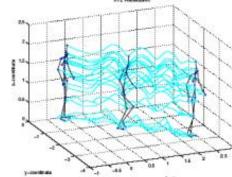
Space-time Approaches

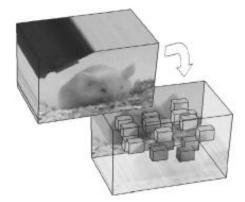
* Space-time approach representation

- * Volume
- * Trajectories
- Local features



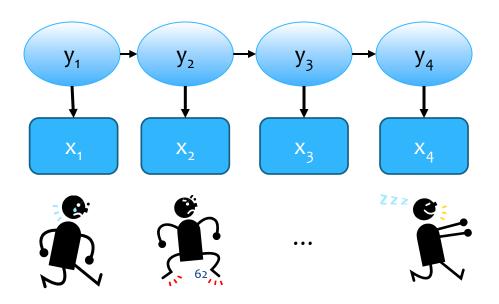
2D nonparametric template matching, Bobick & Davis, IEEE Trans. Pattern Anal. Mach. Intel, 2001



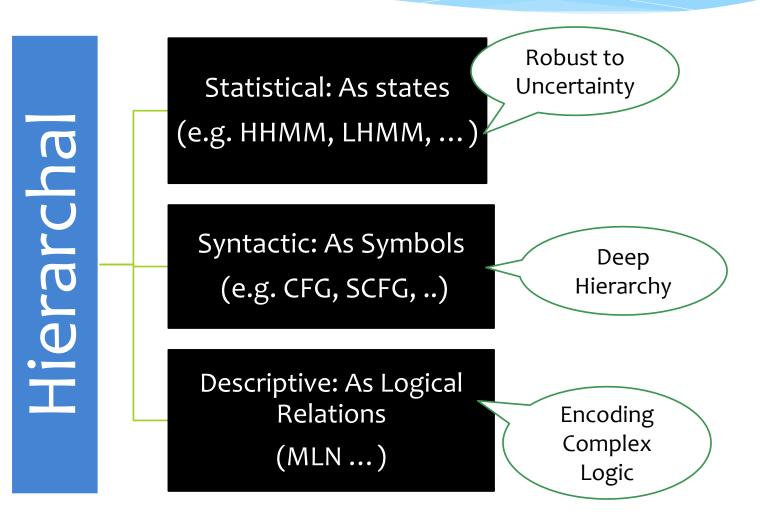


Sequential Approaches

- * Sequential approach
 - * Exemplar:
 - * Directly build template sequence from training examples
 - * State-based
 - * Build a model such as HMM



Hierarchal Approach

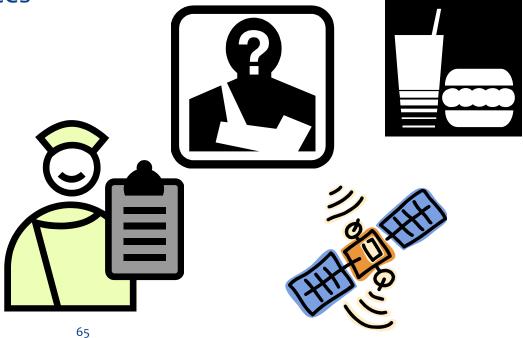


Algorithms & Methods:

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Context Information

- Different types of context data *
 - Information from sensors *
 - Activities and their structure *
 - User profile & preferences *
 - * Static data (e.g. rooms)



Context Modeling Approaches

1. Key-value models

e.g. Context Modeling language (CML)

- 2. Simple markup schema e.g. HomeML
- 3. Ontology

e.g. SOUPA

4. Uncertain context

e.g. Meta-data (e.g. freshness, confidence, resolution)

5. Situation modeling & reasoning

e.g. Situation calculus

Indoor Location Identification

Method	Disadvantage
Smart floor	Physical reconstruction
Infrared motion sensors	Inaccurate, sensing motion (not presence)
Vision	Privacy
Infrared (active badge)	Direct sight
Ultrasonic	Expensive
RFID	Range
WiFi	Interference, inaccurate

Person Identification

- * Multiple residents
 - * Active Identification
 - * RFID Badges
 - * Anonymous
 - * Motion models (Wilson 2005, Crandall 2009)

Reminders

- * Problems [Pollack 2003, Horvitz 2002, 2011]
 - * When to remind?
 - * What to remind?
 - Avoiding activity conflicts
- * Solutions
 - * Planning & scheduling
 - Reinforcement learning



Some Case Studies

Applications

	 Cognitive Orthotics Reminders Planners 	 Navigation and stray prevention
	 Health Monitoring Continuous Monitoring o ADL 	f Vital Signs • Sleep Monitoring
	Therapy & RehabilitationTele-Health	
Help	 Emergency Detection Fall Detection Medical emergency 	
	 Emotional Wellbeing Social Connectedness Facilitating Communication 	on

Reminders

- * Simple reminders
 - * NeuroPager (1994), MAPS (2005), MemoJog (2005)
- * AI-based
 - * PEAT (1997), Autominder (2003)



[Davies 2009]

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Autominder

- * Developed by Martha E. Pollack et al. (U. Of Michigan)
- Reminders about daily activities
 - * Plan manager to store daily plans
 - Resolving potential conflicts
 - Updating the plan as execution proceeds
- * Models plans as Disjunctive Temporal Problems
 - Constraint satisfaction approach
 - Payoff function





- * COACH: Monitoring hand-washing activity and prompting [Mihailidis 2007, U Toronto]
- * Vision
- Detecting current state
 - * Markov Decision process (MDP)
- * Prompting



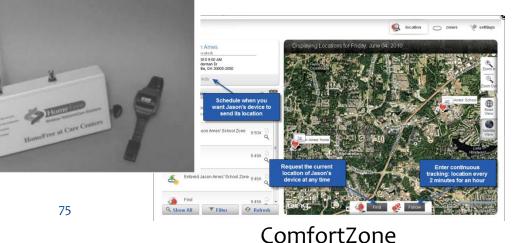


Outdoor Stray Prevention

- * Opportunity Knocks (OK): public transit assistance [Patterson 2004]
- iRoute: Learns walking preference of dementia patients [Hossain 2011]
- * Commercial
 - * GPS shoes
 - * ComfortZone

GPS Shoes

Bracelet for tracking patients



Memory Aid

- * SenseCam
 - * Microsoft Research, Cambridge, UK, 2004-2011
 - * Now commercially available as REVUE









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Example images captured by SenseCam.



Medication Management

MedSignals * Color-coded and numbered dots attach to pill bottles corresponding to drug MD. * Consistently rated easy-to-use by elders Cradle connects to phone line for automatic data uploads and to power to recharge battery Text shows instructions in English or Spanish Separate controls for each bin TAKE 2 TAKE WITH FOOD Braille numbers identify bins SNOOZE Light flashes to indicate which pill bin to open DRUGS DRUG 4 Transparent FDA-approved plastic, Voice Announcements UV-restricting lids allow user to in English or Spanish. Plus see when pill bins need refilling beeps at High, Low or Mute Snooze button delays signals 4 bins for 4 drugs. or skips dose Spaciously holds a month's supply of most drugs, 32 aspirin (325 mg.), for example Stick-on labels with drug names

MedSignals

Case Studies: "CASAS Smart Home"

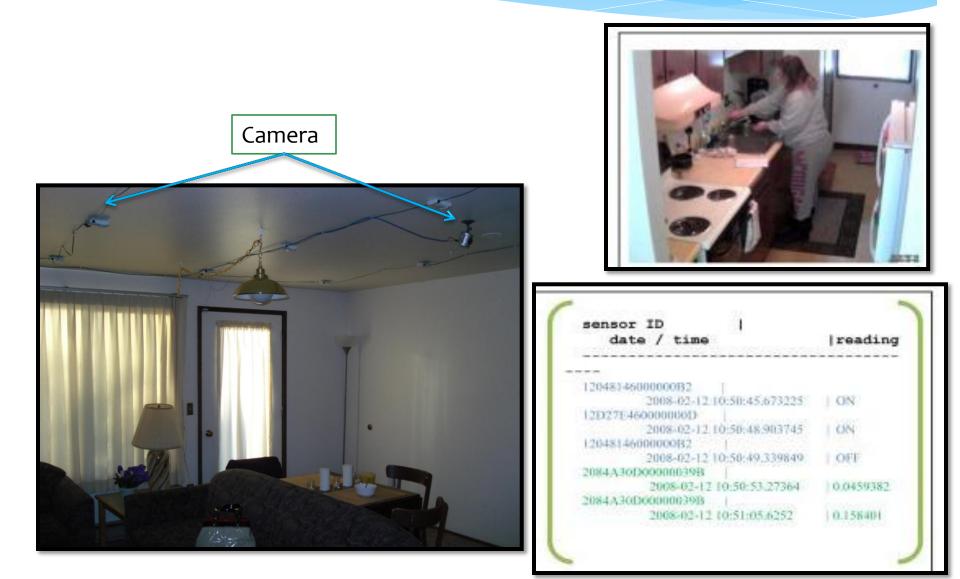
CASAS Project

- * Center for Advanced Studies in Adaptive Systems
- * One of the large-scale smart home projects in the nation
 - * A couple of on campus testbeds
 - * Dozens of real home deployment
- * A smart home data repository

Data Repository

http://ailab.eecs.wsu.edu/casas

On-campus Testbeds

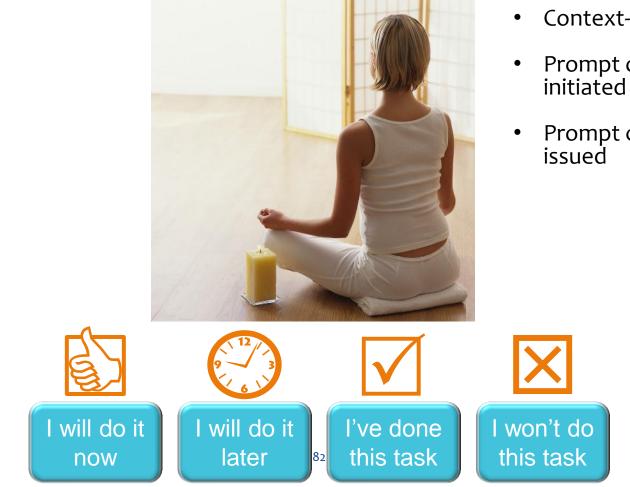


Actual Deployments

- Patients with mild form of dementia
- * Noninvasive deployment
- * Prompting systems



Prompting Technology



- Context-based
- Prompt only if task not
- Prompt can be re-

Design Issues

Wearable & Mobile Design Issues

* Issues:

- * Physical interference with movement
- * Difficulty in removing and placing
- * Weight
- * Frequency and difficulty of maintenance
 - * Charging
 - * Cleaning
- Social and fashion concerns
- * Suggestions:
 - * Use common devices to avoid stigmatization
 - Lightweight
 - * Easy to maintain

User Interface Design Issues

- * Simple Interface
- * Limit possibility of error
- * Avoid cognitive overload
 - * Limit options
 - * keep dialogs linear
 - Avoid parallel tasks
- * Consider all stakeholders
 - Patient, formal onsite/offsite caregivers, informal onsite/offsite caregivers, technical personnel

Privacy & Ethics

* Ethics

- * Perfect transparency
- Control over the system
- * Fight laziness
- * Privacy
 - * Encrypt data
 - * Patient authentication (Owner aware)

Challenges & Future

Are they ready to adopt?

- * Healthy older adults use technology more often*
 - * "Not being perceived as useful" *
- * Better a known devil than an unknown god
- * Privacy Concerns
 - * Big brother
 - Stigmatization

Smart Home Challenges

* Smart homes

- Location detection
 - * Privacy/unobtrusiveness vs. accuracy
 - * Difficulty with multiple residents
 - * PIR sensor proximity is important
- * Reliability
 - * Distinguishing anomalies from normal changes
- * Become more context aware
- Standard protocol

Wearable & Mobile Challenges

- * Wearable & mobile
 - Power harvesting
 - * Size
- Smart fabrics
 - * Limitations when skin is dry or during intense activity
 - * Still hybrid

Assistive Robotics Challenges

* Assistive robotics

- Marketing and price
- * Lack of reliable technology
- * A robot fully capable of helping with all ADLs
- * Adaptive robots
- * More user studies

Legal & Ethical Challenges

* Legal, ethical

- * Telemedicine
 - Lack of regulations
 - * Which state regulations? Patient's or Physician?
 - * Who is responsible for malpractice?
 - * Risk of fake physicians
 - * Physician out-of-state competition
- * Insurance & reimbursement
- * Patient confidentiality



- * Technology
 - * Device interoperability
- Legal issues
- Patient centric
- * Integrate all
 - * Robots + smart home + wearable/mobile sensors + e-textile
- * Technology transfer, go beyond prototype

Resources

Assistive Robotics

* 2011 technical report on "robot assistance for older adults"

 * Understanding the potential for robot assistance for older adults in the home environment (HFA-TR-1102). Smarr, C. A., Fausset, C. B., Rogers, W. A. (2011). Atlanta, GA: Georgia Institute of Technology, School of Psychology, Human Factors and Aging Laboratory.

* 2009 review article on "Assistive social robots in elderly care"

 Broekens J., Heerink M., Rosendal H. Assistive social robots in elderly care: a review. Gerontechnology 2009; 8(2):94-103

* 2011 technical report on "Robot acceptance"

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Wearable Sensors

* Wearable monitoring systems book

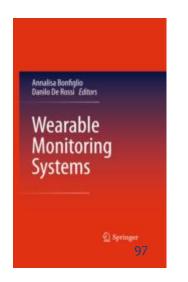
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Excellent tutorial on time series

* Eamonn Keogh's VLDBo6 Tutorial



Activity Recognition

Activity Recognition Book

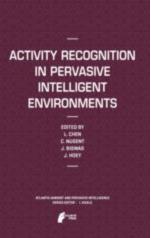
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Smart Homes

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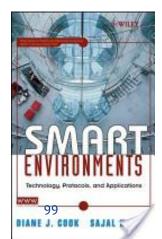
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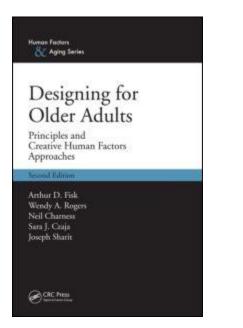
Designing for Older Adults

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Design meets disability

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General Resources

- * **Gerontechnology Journal:** International journal on the fundamental aspects of technology to serve the ageing society
 - * http://www.gerontechnology.info/Journal/
- * Assistive Technology: Journal of Assistive Technologies
 - http://www.emeraldinsight.com/journals.htm?issn=1754-9450
- * Ambient Assisted Living Joint Programme of EU
 - * http://www.aal-europe.eu/

Datasets

* Washington State University CASAS dataset

* http://ailab.eecs.wsu.edu/casas/datasets/index.html

* My collection of links

* http://www.cise.ufl.edu/~prashidi/Datasets/ambientIntelligence.html

* PAIR datasets

* http://homepages.inf.ed.ac.uk/cgeib/PlanRec/Resources.html

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